

A Note on Message Passing Decoding Over Non-Gaussian Channels

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Abstract

In these notes, the authors work out the outline of the analysis of SPARC codes when the channel model is free space optical (FSO). In this study, the fading coefficient is assumed to be a known constant. The key contribution is an application of Shannon's standard noisy channel coding theorem to the aforementioned channel model.

1 Fading Coefficients are Known Constants: Channel Model and Initial Time

In this section we setup the case where the fading coefficient of the FSO channel is known. Then we input a SPARC codeword [1] into the channel. Then we step forward in time using the AMP algorithm and obtain the decoding estimate for the input codeword coordinate (see Equation 26 in Subsection 1.2). Working this out explicitly sets the stage for an application of the Shannon theorem in Section 2.

$$x = \text{Coeff}_{FSO} \cdot A\beta_0 \quad (1)$$

where Coeff_{FSO} is known and $A\beta_0$ is a single codeword coordinate. We have the channel equation,

$$Y = Hx + I_{th} \quad (2)$$

where H is treated as a constant at present. Next we let

$$J = \frac{Y}{H} = x + \frac{I_{th}}{H}. \quad (3)$$

where J represents a single number and H represents a single fading coefficient. We assume H is known. Therefore,

$$J_i = \text{Coeff}_{FSO}(A\beta_0)_i + \frac{I_{th}}{H_i}. \quad (4)$$

Since $Coeff_{FSO}$ is a known constant,

$$K_i \equiv \frac{J_i}{Coeff_{FSO}} = (A\beta)_i + \frac{I_{th}}{Coeff_{FSO} \cdot H_i} \quad (5)$$

where A is a known, sparse, design matrix, β is a sparse message vector and the last term is the noise term. In vector form,

$$\vec{K} = \vec{A}\vec{\beta}_0 + \vec{n} \quad (6)$$

which belongs to $\mathbf{R}^n$ with $\vec{\beta}_0 \in \mathbf{R}^N$. Here $\vec{A}$ is the design matrix of the SPARC code, $\vec{\beta}_0$ is the message vector and $\vec{n}$ is the i.i.d. noise vector. The variance of each i.i.d. r.v. is $\frac{I_{th}^2}{(Coeff_{FSO} H_i)^2}$ where $Coeff_{FSO} = 2\mathcal{R}P\sqrt{T}$ and H_i is a known constant. Given $\vec{K}$ and $\vec{A}^1$, we wish to reconstruct $\vec{\beta}_0$.

Next, we will advance through the AMP algorithm steps, indexed by the time t . We start with Step 1, at time $t = 0$. We guess $\beta_0^0 = 0$. Therefore,

$$z^0 = \vec{K} - \vec{A}\beta_0^0 + \frac{1}{\delta} z^{-1} \frac{1}{N} \sum_{i=1}^N \eta'_{-1}(\vec{A}^\dagger z^{-1} + \beta_0^{-1}) \quad (7)$$

where $\delta = \frac{n}{LM}$. Further, any variable with a negative index is assumed to be 0, as per Montanari. Thus,

$$z^{-1} \equiv 0 \quad (8)$$

$$\eta'_{-1} \equiv 0 \quad (9)$$

and

$$\beta_0^{-1} \equiv 0. \quad (10)$$

Therefore,

$$z^0 = \vec{K} - \vec{A}\beta_0^0 + 0 \quad (11)$$

with $\beta_0^0 = 0$. Therefore,

$$z^0 = \vec{K}. \quad (12)$$

¹Note that this design matrix is $n \times LM$, with $N \equiv LM$.

1.1 First Time Step

Next,

$$\beta_0^1 = \eta_0(\vec{A}^\dagger z^0 + \beta_0^0) \quad (13)$$

where

$$z^0 = \vec{K} \quad (14)$$

and $\beta_0^0 = 0$. Further,

$$\eta_0 \equiv \eta_i^0|_{i=0}(s) \quad (15)$$

and

$$\eta_i^0 = \sqrt{nP_l} \frac{e^{s_i \frac{\sqrt{nP_l}}{\tau_0^2}}}{\sum_{j \in \text{sec}(i)} e^{s_j \frac{\sqrt{nP_l}}{\tau_0^2}}} \quad (16)$$

where $1 \leq i \leq N$. Evaluating the expression at $i = 0$, we get

$$\eta_0 = \sqrt{nP_l} \frac{e^{s_0 \frac{\sqrt{nP_l}}{\tau_0^2}}}{\sum_{j \in \text{sec}(0)} e^{s_j \frac{\sqrt{nP_l}}{\tau_0^2}}} \quad (17)$$

We define,

$$\tau_0^2 \equiv \frac{\overline{i_{th}^2}}{(2\mathcal{R}P\sqrt{T}H_i)^2} + \frac{\mathbb{E}[\beta_0^2]}{\delta} \quad (18)$$

where β_0 is a random variable whose distribution coincides with the empirical distribution of the entries of $\vec{\beta}_0$. This is based on Equation (1.4) and adjoining text from Montanari's paper [2], and Equation [8] of the reference DMM09 from the same paper. Here $\delta = \frac{n}{LM}$ and P_l is the allocated power.

We find,

$$z^1 = \vec{K} - \vec{A} \beta_0^0 + \frac{1}{\delta} z^0 \langle \eta_0'(\vec{A}^\dagger z^0 + x^0) \rangle \quad (19)$$

where $z^0 = \vec{K}$ and $x^0 = 0^2$. Recall that η_0' was specified earlier. Therefore,

$$z^1 = \vec{K} + \frac{1}{\delta} \vec{K} \langle \eta_0' \vec{A}^\dagger \vec{K} \rangle. \quad (20)$$

²Note that: $\beta_0 \equiv x$, $\beta_0^0 \equiv x^0, \dots, \beta_0^t \equiv x^t$.

1.2 Second Time Step

Then

$$\beta_0^2 = \eta_1(\vec{A}^\dagger z^1 + \beta_0^1). \quad (21)$$

Here we ask the question as to what is τ_1^2 , which is needed in η_1 ? We refer the reader to Equation (1.4) from Montanari's paper. There,

$$\tau_1^2 = \frac{\overline{i_{th}}^2}{(2\mathcal{R}P\sqrt{TH_i})^2} + \frac{1}{\delta}\mathbb{E}[\eta_0(\beta_0 + \tau_0 z) - \beta_0]^2 \quad (22)$$

where η_0 is specified in $\perp$, β_0 has a pdf which matches the empirical distribution of the entries of $\vec{\beta}_0$ and $z \sim \mathcal{N}(0, 1)$ is independent of β_0 . Further, Equation (18) specifies τ_0 . Next,

$$z^2 = \vec{K} - \vec{A}\eta_1(\vec{A}^\dagger z^1 + \beta_0^1) + \frac{1}{\delta}z^1\langle\eta_1'(\vec{A}^\dagger z^1 + \beta_0^1)\rangle \quad (23)$$

and so therefore,

$$z^2 = \vec{K} - \vec{A}\eta_1(\vec{A}^\dagger z^1 + \beta_0^1) + \frac{1}{\delta}z^1\langle\eta_1'(\vec{A}^\dagger z^1 + \beta_0^1)\rangle. \quad (24)$$

Therefore,

$$z^2 = \vec{K} - \vec{A}\eta_1(\vec{A}^\dagger (\vec{K} + \frac{1}{\delta}\vec{K}\langle\eta_0'\vec{A}^\dagger\vec{K}\rangle) + \beta_0^1) \dots \quad (25)$$

$$\dots + \frac{1}{\delta}(\vec{K} + \frac{1}{\delta}\vec{K}\langle\eta_0'\vec{A}^\dagger\vec{K}\rangle)\langle\eta_1'(\vec{A}^\dagger (\vec{K} + \frac{1}{\delta}\vec{K}\langle\eta_0'\vec{A}^\dagger\vec{K}\rangle) + \beta_0^1)\rangle. \quad (26)$$

and so on, for the higher indices.

Thus, we have a nested or iterative z^t from which we reconstruct β_0^{t+1} using Montanari's Equation (1.1), and that gives us, for large enough t , a good approximation to β_0 .

2 Analysis Outline

In this section, our goal is to characterize the performance of the SPARC-FSO-AMP system. We break down the characterization into a sequence of steps.

1. We fix some large t
2. Get the equation for β_0^{t+1} , as in the parts above. It will be in terms of the received vector, $\vec{k}$, the empirical distribution of the message vector (via τ), $\vec{P}_{\vec{\beta}_0}$, the power allocation P_l , the SPARC structure ($s_i, s_j, \text{sec}(j)$ etc.) and FSO channel-noise and modulation constants.

3. Assume a uniform distribution on the messages and derive $\widetilde{P_{\beta_0}}$.
4. Fix a power allocation P_l , for example an exponential power allocation.
5. Fix the SPARC structure $s_i, s_j, \text{sec}(j)$ etc.
6. Fix the channel noise and modulation parameters as constants.
7. Thus we have,

$$\beta_0^{t+1} \sim f(\vec{K}, \widetilde{P_{\beta_0}}, P_l, s_i, s_j, I_{th}, H). \quad (27)$$

Define $R' \equiv (\widetilde{P_{\beta_0}}, P_l, s_i, s_j, I_{th}, H)$. That is, $\beta_0^{t+1} \sim g(\vec{K})$, since R' is known, where $\vec{K}$ was received and β_0^{t+1} is our approximation to the message vector of the pseudo-channel.

8. Finally, using $g(\vec{K})$ as the decoding, we are done.
9. Then we compare $g(\vec{K})$ with β_0 to determine whether the decoding is correct and thus the overall transmission goal is met or not.
10. So we want the following quantity:

$$Pr\{\beta_0 \neq g(\vec{K})\} \quad (28)$$

11. For different t , we could say that since the decoding structure was different, the code is different.
12. As $t \rightarrow \infty$, we have here a sequence of codes.
13. Recall the noisy channel coding theorem: for every rate $R < C$, there exists a sequence of codes whose $Poe_{max} \rightarrow 0$ as $t \rightarrow \infty$.³
14. Thus, fix a rate R and so a SPARC structure (L, n, N) and then we have here a customized (that is, (L, n, N) -dependent) code for each t . That is, we have a code sequence. Find the maximum value of R such that Equation (28) converges to 0 as $t \rightarrow \infty$. This would be the “capacity” or maximum achievable rate R_{max} on an FSO, using the SPARC-AMP code.
15. Finally, we may compare this R_{max} with LDPC-FSO-Belief-Propagation code’s maximum achievable rate to decide whether SPARCs are “better” vis-a-vis LDPC codes.

³Note that Equation (1) in Greig-Venkataramanan states that

$$R = \frac{L \log(M)}{n} = \frac{L}{n} (\log \frac{N}{L}) \quad (29)$$

where L is the number of sections and n, N are dimensional parameters.

3 Conclusion

In this note we have setup the exact analysis outline to determine the comparative performance of different codes such as LDPC and SPARCs over the free space optical channel with approximate message passing decoding. Note that the channel model of the FSO system is itself under development, with effects such as turbulence not fully accounted for yet in the literature (see the text of Andrews and Phillips for example), and therefore the steps presented in this work, if used with the basic model should be taken with some degree of uncertainty.

If such a coding/decoding system is to be used in the control setting for say synchronization, then Sahai's anytime framework will need to be integrated within this setup. One imagines a sequential semi-orthogonal repeated pulse position modulation system, but with AMP decoding which itself plays out online. The coding side will need to be reformulated as well. Some steps in this direction were taken in the following preprint: [3].

References

- [1] Kuan Hsieh and Ramji Venkataramanan. Modulated sparse superposition codes for the complex awgn channel. *IEEE Transactions on Information Theory*, 67(7):4385–4404, 2021.
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- [3] Aman Chawla. Anytime reliability analysis of finite state slow fading free space optical channels. June 2025.